

Architecture of ML Systems (AMLS)

03 Compilation – Size Inference and Rewrites

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Last update: May 02, 2024



Announcements / Org



■ #1 Hybrid & Video Recording

- Hybrid lectures (in-person, zoom) with optional attendance

<https://tu-berlin.zoom.us/j/9529634787?pwd=R1ZsN1M3SC9BOU1OcFdmem9zT202UT09>

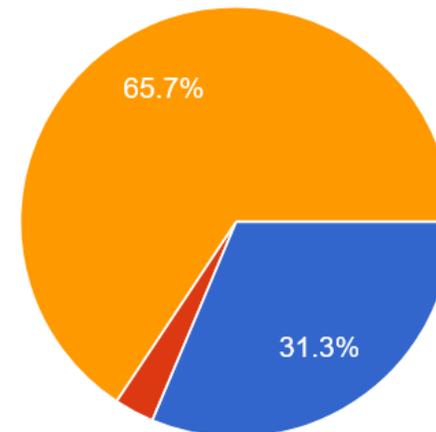
- Zoom **video recordings**, links from website

https://mboehm7.github.io/teaching/ss24_amlis/index.htm



■ #2 Projects / Alternative Exercise

- **Task description** on course website since Apr 15
- **Project Selection by Apr 29**, Submission by **July 08**
- Some late registrations (it's ok), exercise registrations still possible



- SystemDS Project
- DAPHNE Project
- Alternative Exercise

66/220
registered
(50 student teams)



Agenda

- **Compilation Overview**
- **Size Inference and Cost Estimation**
- **Rewrites (and Operator Selection)**



SystemDS, and several other ML systems

Compilation Overview

Recap: Linear Algebra Systems



■ Comparison Query Optimization

- Rule- and cost-based rewrites and operator ordering
- Physical operator selection and query compilation
- Linear algebra / other ML operators, DAGs, control flow, sparse/dense formats

■ #1 Interpretation (operation at-a-time)

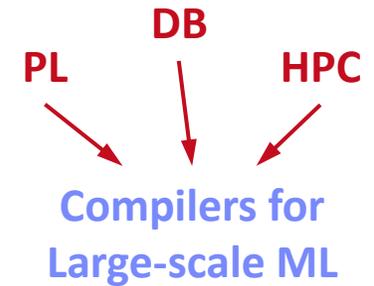
- Examples: **R**, **PyTorch**, **Morpheus** [PVLDB'17]

■ #2 Lazy Expression Compilation (DAG at-a-time)

- Examples: **RIOT** [CIDR'09], **TensorFlow** [OSDI'16]
Mahout Samsara [MLSystems'16]
- Examples w/ control structures: **Weld** [CIDR'17],
OptiML [ICML'11], **Emma** [SIGMOD'15]

■ #3 Program Compilation (entire program)

- Examples: **SystemML** [PVLDB'16], **Julia**
Cumulon [SIGMOD'13], **Tupleware** [PVLDB'15]



Optimization Scope

```
1: X = read($1); # n x m matrix
2: y = read($2); # n x 1 vector
3: maxi = 50; lambda = 0.001;
4: intercept = $3;
5: ...
6: r = -(t(X) ** y);
7: norm_r2 = sum(r * r); p = -r;
8: w = matrix(0, ncol(X), 1); i = 0;
9: while(i < maxi & norm_r2 > norm_r2_trgt)
10: {
11:   q = (t(X) ** X ** p) + lambda * p;
12:   alpha = norm_r2 / sum(p * q);
13:   w = w + alpha * p;
14:   old_norm_r2 = norm_r2;
15:   r = r + alpha * q;
16:   norm_r2 = sum(r * r);
17:   beta = norm_r2 / old_norm_r2;
18:   p = -r + beta * p; i = i + 1;
19: }
20: write(w, $4, format="text");
```

ML Program Compilation / Graphs



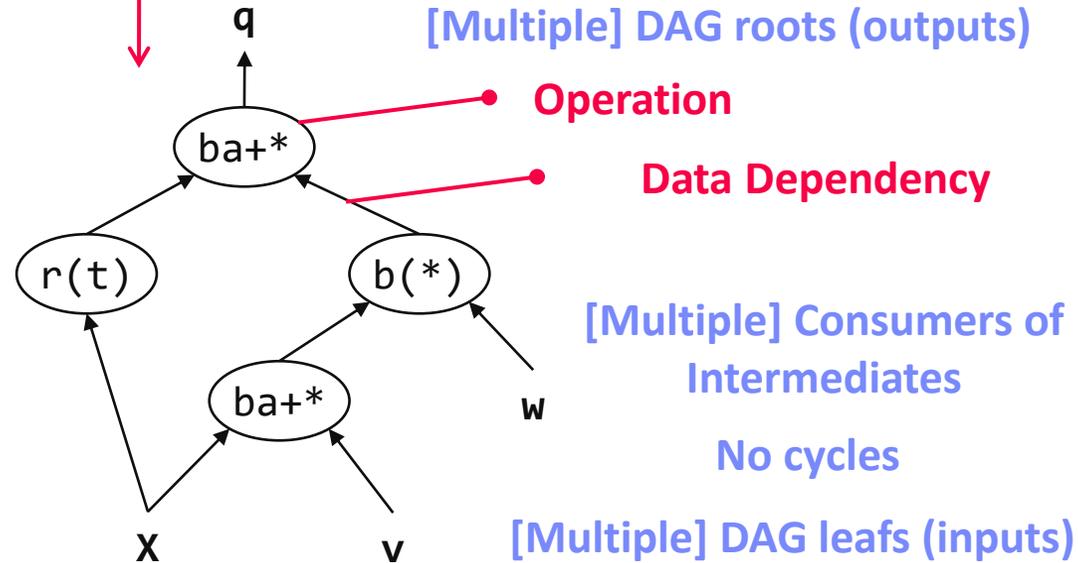
Script:

```
while(...) {  
  q = t(X) %*% (w * (X %*% v)) ...  
}
```

Statement
Block
Hierarchy

Operator DAG (today's lecture)

- a.k.a. “graph”
(data flow graph)
- a.k.a. intermediate
representation (IR)



Runtime Plan

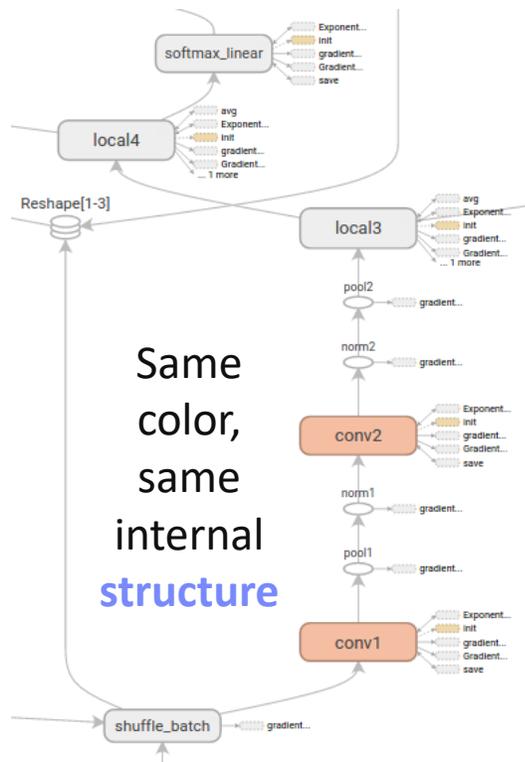
- Compiled runtime plans
- Interpreted plans

```
SPARK mapmmchain X.MATRIX.DOUBLE w.MATRIX.DOUBLE  
v.MATRIX.DOUBLE _mVar4.MATRIX.DOUBLE XtwXv
```

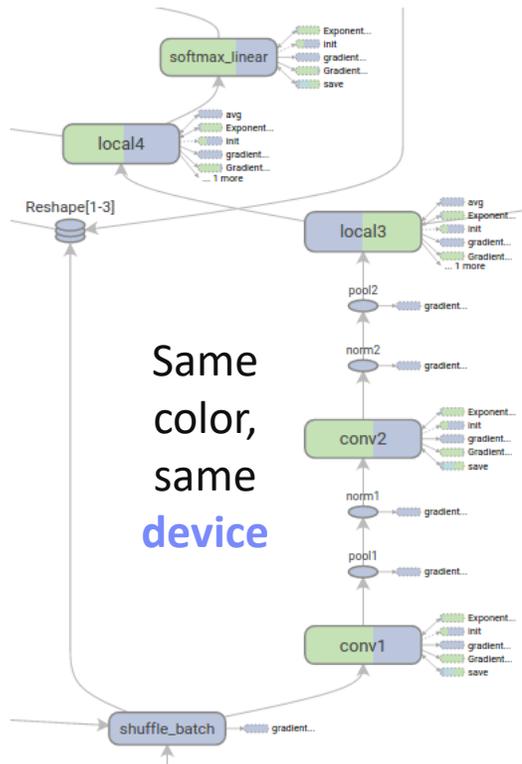


Example TF TensorBoard

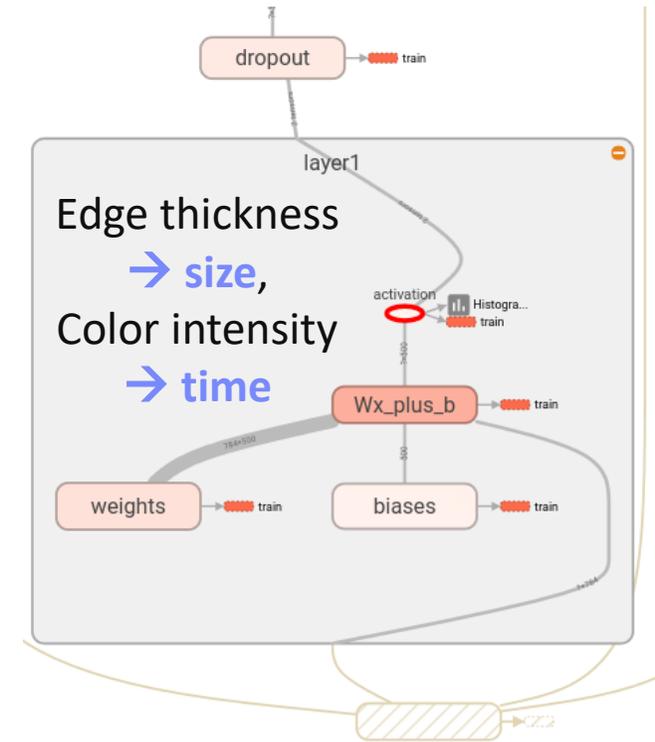
(Node) Structure View



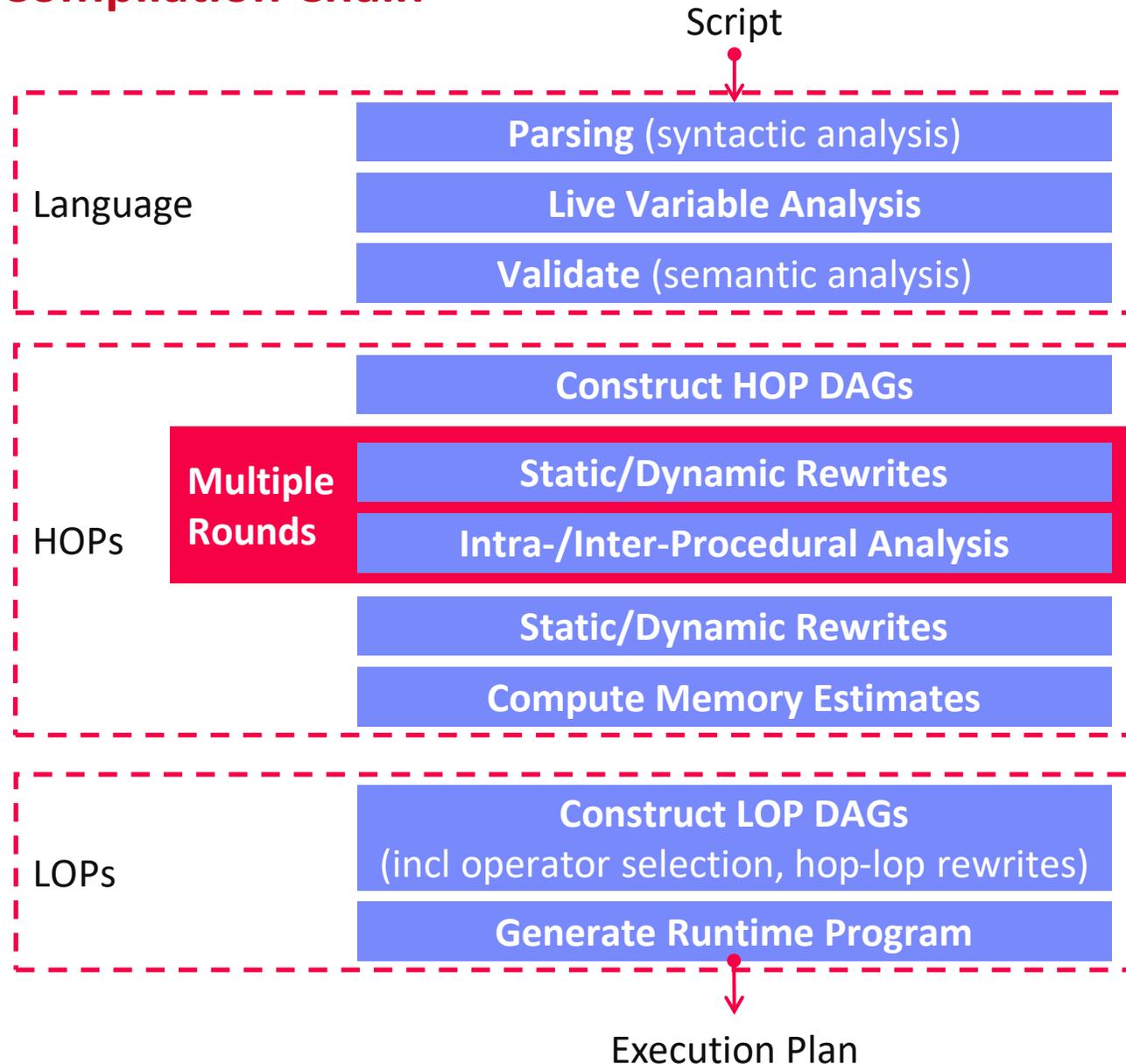
Device View (CPU, GPU)



Tensor Shapes and Runtime Statistics (time, mem)



Example SystemDS: Compilation Chain



[Matthias Boehm et al:
SystemML's Optimizer:
Plan Generation for
Large-Scale Machine
Learning Programs. **IEEE
Data Eng. Bull** 2014]



**Dynamic
Recompilation
(lecture 04)**

Example SystemDS: Basic HOP and LOP DAG Compilation



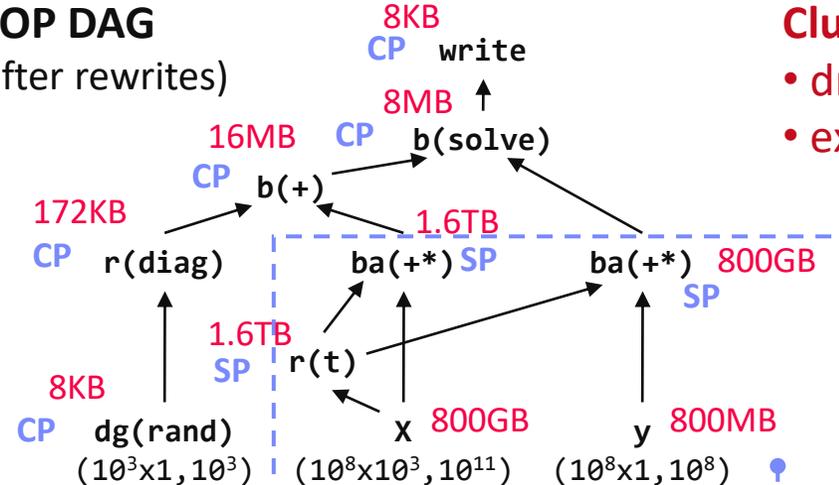
LinregDS (Direct Solve)

```
X = read($1);
y = read($2);
intercept = $3;
lambda = 0.001;
...
```

Scenario:
 $X: 10^8 \times 10^3, 10^{11}$
 $y: 10^8 \times 1, 10^8$

```
if( intercept == 1 ) {
  ones = matrix(1, nrow(X), 1);
  X = append(X, ones);
}
I = matrix(1, ncol(X), 1);
A = t(X) %*% X + diag(I)*lambda;
b = t(X) %*% y;
beta = solve(A, b);
...
write(beta, $4);
```

HOP DAG (after rewrites)



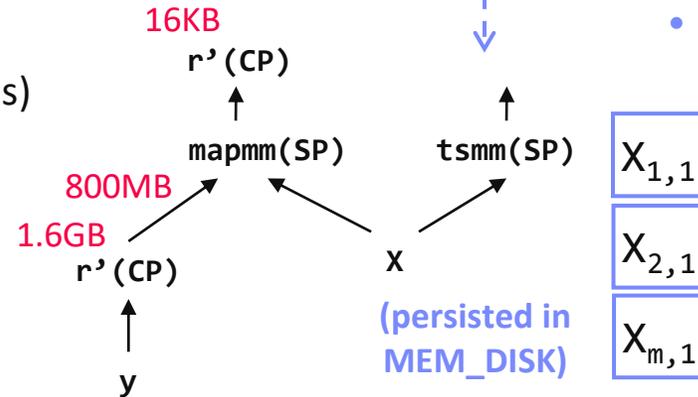
Cluster Config:

- driver mem: 20 GB
- exec mem: 60 GB

→ Distributed Matrices

- Fixed-size matrix blocks
- Data-parallel operations

LOP DAG (after rewrites)



→ Hybrid Runtime Plans:

- Size propagation / memory estimates
- Integrated CP / Spark runtime
- Dynamic recompilation during runtime



Size Inference and Cost Estimation

**Crucial for Generating Valid Execution Plans
& Cost-based Optimization**

Size Propagation / Shape Inference

Size Information

- Dimensions (#rows, #columns)
- Sparsity (#nnz/(#rows * #columns))

→ memory estimates and costs

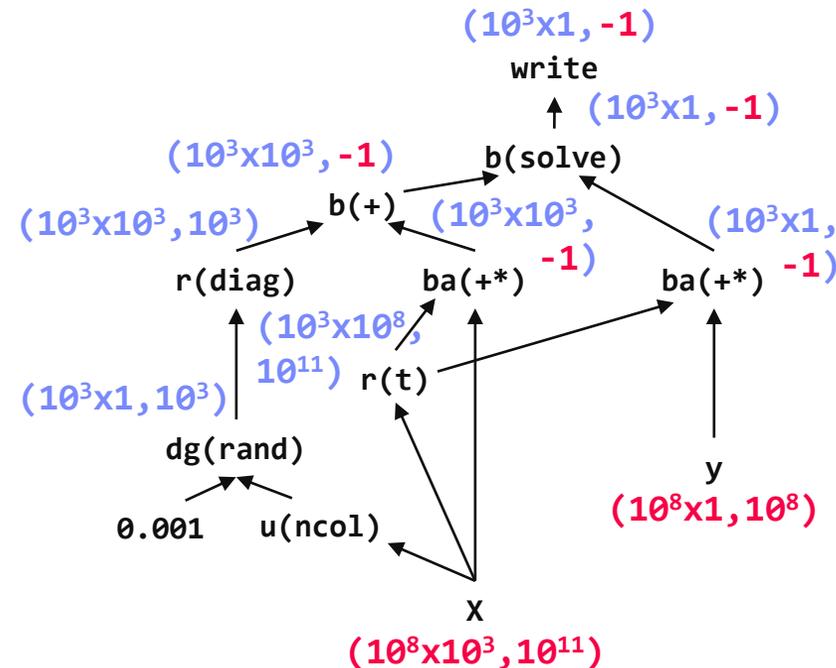
Principle: Worst-case Assumption

- Necessary for guarantees (memory)

DAG-level Size Propagation

- **Input:** Size information for leaves
- **Output:** size information for all operators, -1 if still unknown
- Propagation based on operation semantics (single bottom-up pass over DAG)

```
X = read($1);
y = read($2);
I = matrix(0.001, ncol(X), 1);
A = t(X) %*% X + diag(I);
b = t(X) %*% y;
beta = solve(A, b);
```



Size Propagation / Shape Inference, cont.

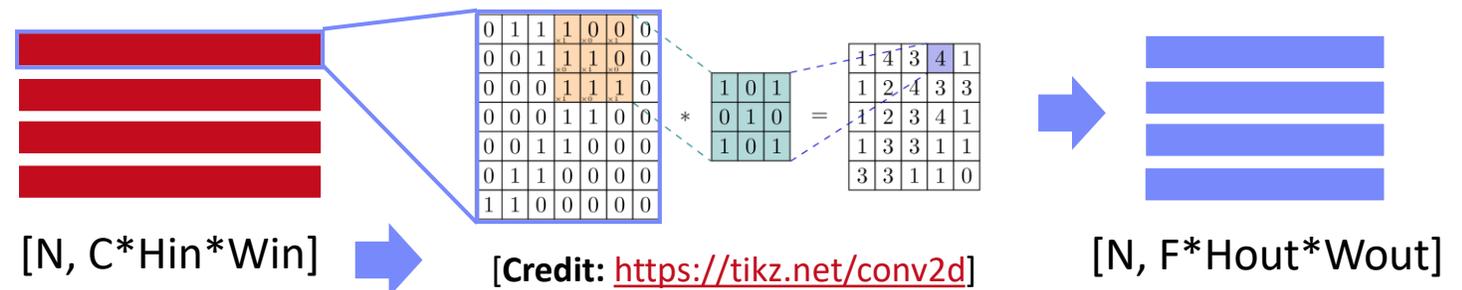


Basic Linear Algebra Examples

Operation	Inputs	Output
Matrix multiplication $A \% * \% B$	$[M, N] \% * \% [N, L]$	$[M, L]$
Element-wise matrix-matrix addition $A + B$	$[M, N] + [M, N]$	$[M, N]$
Element-wise matrix-vector addition $A + b$	$[M, N] + [M, 1]$	$[M, N]$
Matrix transposition	$[M, N]$	$[N, M]$
Matrix diagonal (M2V)	$[M, M]$	$[M, 1]$
Unary matrix aggregation $\text{colSums}(A)$	$[M, N]$	$[1, N]$

Conv2d Example

- Input: mini-batch of images in linearized row representation
- C .. num channels, F .. num filters
- Hin x Win (height x width)
- Stride (default 1), pad (default 0)



$$\text{Hout} = \text{as.integer}(\text{floor}((\text{Hin} + 2 * \text{padh} - \text{Hf}) / \text{strideh} + 1))$$

$$\text{Wout} = \text{as.integer}(\text{floor}((\text{Win} + 2 * \text{padw} - \text{Wf}) / \text{stridew} + 1))$$

Size Propagation / Shape Inference, cont.



Example SystemDS

- Hop refreshSizeInformation() (exact)
- Hop inferOutputCharacteristics()
- Compiler explicitly differentiates between exact and other size information
- **Note:** ops like aggregate, ctable, rmEmpty challenging but w/ upper bounds

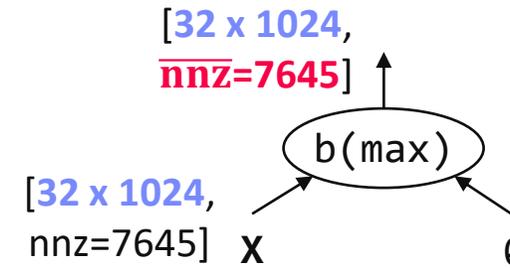
Example TensorFlow

- Operator registrations
- Shape inference functions



```
REGISTER_OP("Relu")  
  .Input("features: T")  
  .Output("activations: T")  
  .Attr("T: {realnumbertype, qint8}")  
  .SetShapeFn(  
    shape_inference::UnchangedShape)
```

Example Relu (rectified linear unit)



[Alex Passos: Inside TensorFlow – Eager execution runtime, <https://www.youtube.com/watch?v=qjx65mD6nrc>, Dec 2019]



Constant and Size Propagation

▪ Constant Propagation

- Relies on live variable analysis
- Propagate constant literals into read-only statement blocks

▪ Program-level Size Propagation

- Relies on **constant propagation** and **DAG-level size propagation**
- **Propagate size information across conditional control flow:** size in leafs, DAG-level prop, extract roots
- **if:** reconcile if and else branch outputs
- **while/for:** reconcile pre and post loop, reset if pre/post different

```

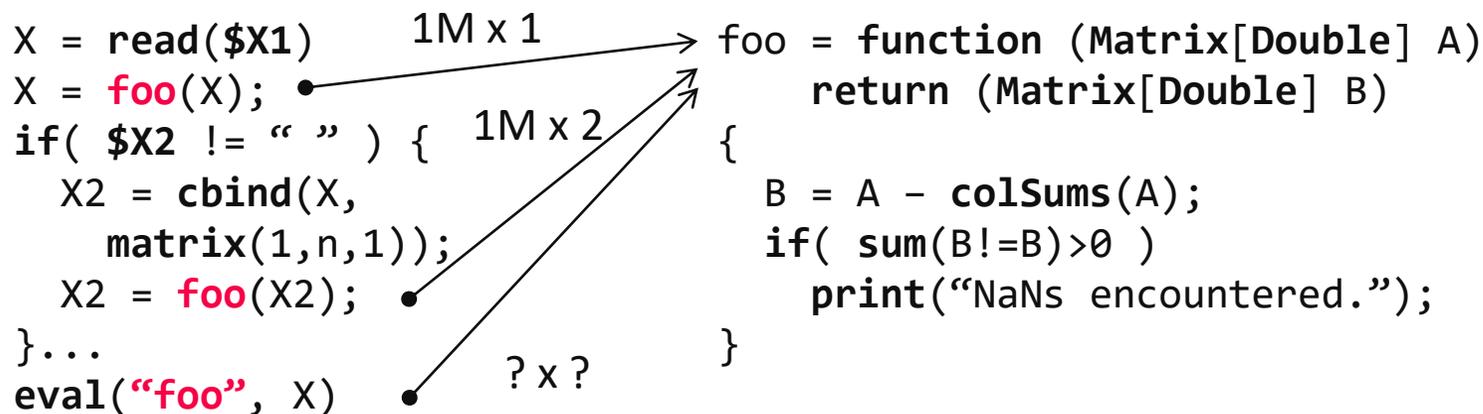
X = read($1); # n x m matrix
y = read($2); # n x 1 vector
maxi = 50; lambda = 0.001;
if(...){ }
r = -(t(X) %*% y);
r2 = sum(r * r);
p = -r; # m x 1
w = matrix(0, ncol(X), 1); # m x 1
i = 0;
while(i < maxi & r2 > r2_trgt) {
    q = (t(X) %*% X %*% p) + lambda * p;
    alpha = norm_r2 / sum(p * q);
    w = w + alpha * p; # m x 1
    old_norm_r2 = norm_r2;
    r = r + alpha * q;
    r2 = sum(r * r);
    beta = norm_r2 / old_norm_r2;
    p = -r + beta * p; # m x 1
    i = i + 1;
}
write(w, $4, format="text");

```

Inter-Procedural Analysis

- **Intra/Inter-Procedural Analysis (IPA)**

- Integrates all size propagation techniques (**DAG+program**, **size+constants**)
- Intra-function and inter-function size propagation (**called once**, **consistent sizes**, **consistent literals**)



- **Additional IPA Passes (selection)**

- **Inline functions** (single statement block, small)
- **Dead code elimination** and simplification rewrites
- Remove unused functions & flag recompile-once

```
//create ordered list of IPA passes
_passes = new ArrayList<>();
_passes.add(new IPAPassRemoveUnusedFunctions());
_passes.add(new IPAPassFlagFunctionsRecompileOnce());
_passes.add(new IPAPassRemoveUnnecessaryCheckpoints());
_passes.add(new IPAPassRemoveConstantBinaryOps());
_passes.add(new IPAPassPropagateReplaceliterals());
_passes.add(new IPAPassInlineFunctions());
_passes.add(new IPAPassEliminateDeadCode());
_passes.add(new IPAPassFlagNonDeterminism());
//note: apply rewrites last because statement block rewrites
//might merge relevant statement blocks in special cases, which
//would require an update of the function call graph
_passes.add(new IPAPassForwardFunctionCalls());
_passes.add(new IPAPassApplyStaticAndDynamicHopRewrites());
```

Sparsity Estimation Overview



■ Motivation

- **Sparse input matrices** from NLP, graph analytics, recommender systems, scientific computing
- **Sparse intermediates** (transform, selection, dropout)
- **Selection/permutation matrices**

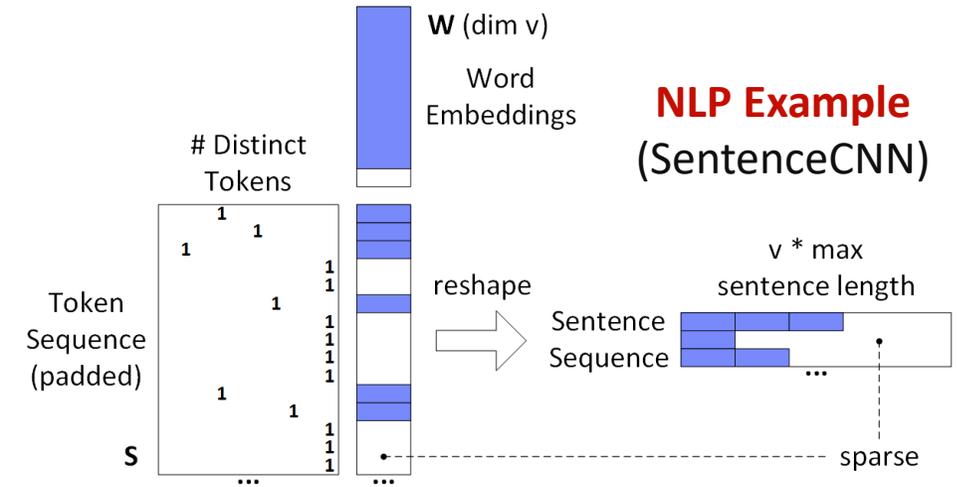


■ Problem Definition

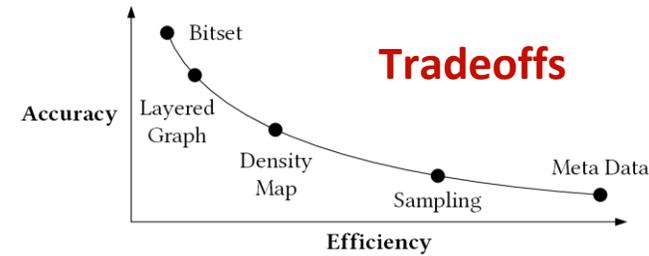
- Sparsity estimates used for **format decisions, output allocation, cost estimates**
- Matrix A with sparsity $s_A = \text{nnz}(A)/(mn)$ and matrix B with $s_B = \text{nnz}(B)/(nl)$
- Estimate sparsity $s_C = \text{nnz}(C)/(ml)$ of matrix product $C = A B$; $d = \max(m, n, l)$
- **Assumptions**
 - **A1:** No cancellation errors
 - **A2:** No not-a-number (NaN)



Common assumptions
→ **Boolean matrix product**



Sparsity Estimation – Estimators



Overview

#1 Naïve Metadata Estimators

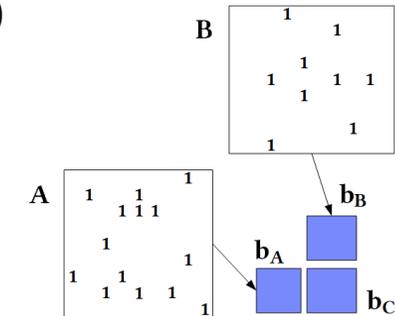
- Derive the output sparsity solely from the sparsity of inputs (e.g., [SystemDS](#))

$$\hat{S}_C = 1 - (1 - s_A s_B)^n$$

$$\hat{S}_C = \min(1, s_A n) \cdot \min(1, s_B n)$$

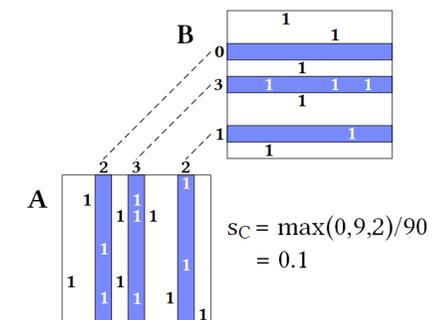
#2 Naïve Bitset Estimator

- Convert inputs to bitsets, perform Boolean mm (per row)
- Examples: [SciDB](#) [SSDBM'11], [NVIDIA cuSparse](#), [Intel MKL](#)



#3 Sampling

- Take a sample of aligned columns of A and rows of B
- Sparsity estimated via max of count-products
- Examples: [MatFast](#) [ICDE'17], improvements in paper

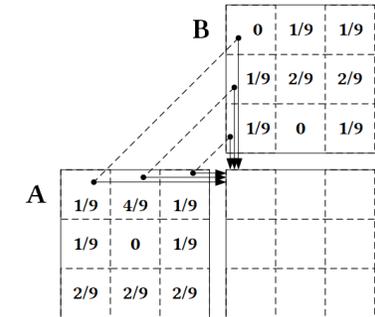


Sparsity Estimation – Estimators, cont.



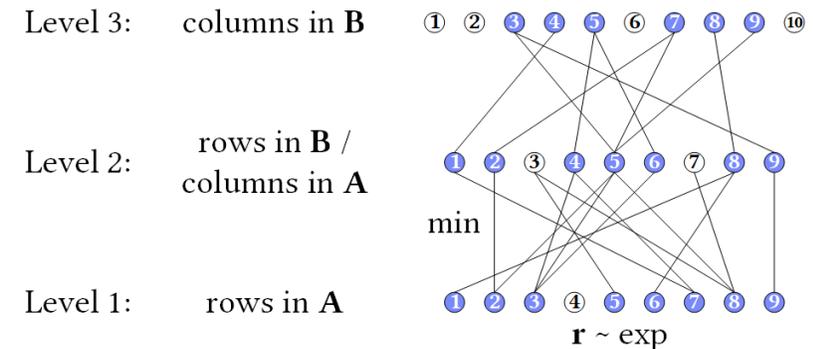
#4 Density Map

- Store sparsity per $b \times b$ block (default $b = 256$)
- MM-like estimator (average case estimator for $*$, probabilistic propagation $s_A + s_B - s_A s_B$ for $+$)
- Example: [SpMacho](#) [EDBT'15], [AT Matrix](#) [ICDE'16]



#5 Layered Graph [J.Comb.Opt.'98]

- Nodes:** rows/columns in mm chain
- Edges:** non-zeros connecting rows/columns
- Assign r -vectors $\sim \exp(w/\lambda=1)$ and propagate via elementwise min
- Intuition:** KMV (the more paths the larger the values)
- Estimate over roots (output columns)



$$\hat{s}_C = \left(\sum_{v \in \text{roots}} \frac{|\mathbf{r}_v| - 1}{\text{sum}(\mathbf{r}_v)} \right) / (ml),$$



[Edith Cohen: Structure Prediction and Computation of Sparse Matrix Products. **Journal of Combinatorial Optimization** 1998]



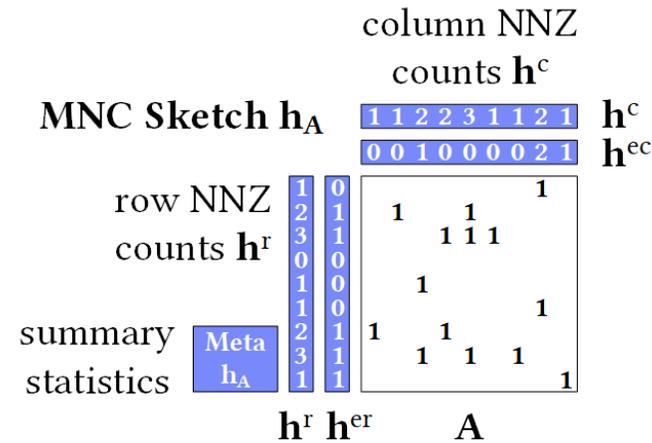
Sparsity Estimation – Estimators, cont.



- #6 MNC Sketch (Matrix Non-zero Count)**
 - Create MNC sketch for inputs A and B
 - Exploitation of structural properties (e.g., 1 non-zero per row, row sparsity)
 - Support for matrix expressions (reorganizations, elementwise ops)
 - Construction:** $O(d)$ space, $O(\text{nnz})$ time
 - Sketch propagation and estimation

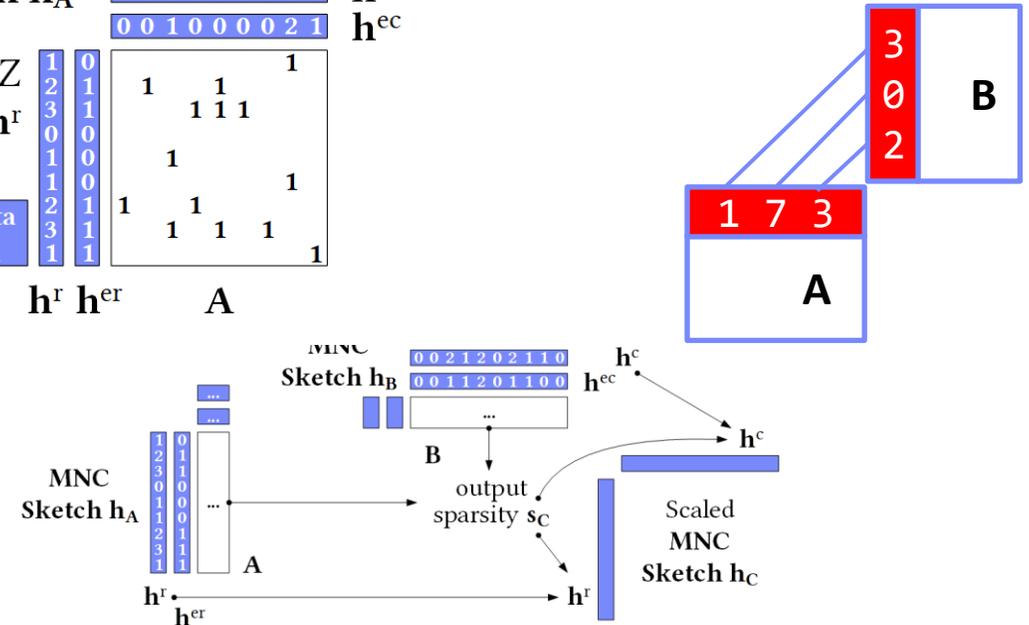


[Johanna Sommer, Matthias Boehm, Alexandre V. Evfimievski, Berthold Reinwald, Peter J. Haas: **MNC**: Structure-Exploiting Sparsity Estimation for Matrix Expressions. **SIGMOD 2019**]



$$s_C = \hat{s}_C = h_A^c h_B^r / (ml)$$

if $\max(h_A^r) \leq 1 \vee \max(h_B^c) \leq 1$



- #7 RS Estimator (Row-wise Sparsity)**

[Chunxu Lin, Wensheng Luo, Yixiang Fang, Chenhao Ma, Xilin Liu, Yuchi Ma: On Efficient Large Sparse Matrix Chain Multiplication, **SIGMOD 2024**]



Memory Estimates and Costing



■ Memory Estimates

- **Matrix memory estimate** := based on the dimensions and sparsity, decide the format (sparse, dense) and estimate the size in memory
- **Operation memory estimate** := input, intermediates, output
- **Worst-case sparsity estimates** (**upper bound**)

■ #1 Costing at Logical vs Physical Level

- Costing at physical level takes physical ops and rewrites into account but is much more costly

■ #2 Costing Operators/Graphs vs Plans

- Costing plans requires heuristics for **# iterations**, **branches** in general

■ #3 Analytical vs Trained Cost Models

- Analytical: **estimate I/O and compute workload**
- Training: **build regression models** for individual ops

A Personal War Story

Physical, Plans,
Trained
[PVLDB 2014]



Physical, Plans,
Analytical
[SIGMOD 2015]



Logical, Graphs,
Analytical
[PVLDB 2018]



Example Analytical Cost Model



Hardware Setting

Max Memory Bandwidth:

2 sockets * 6 channels * 21.9 GB/s = **264 GB/s**

Max Compute:

2 sockets * 28 cores * 2.2 GHz * 2 FMA units
* 8 FP64 (AVX512) * 2 (FMA) = **3.85 TFLOP/s**

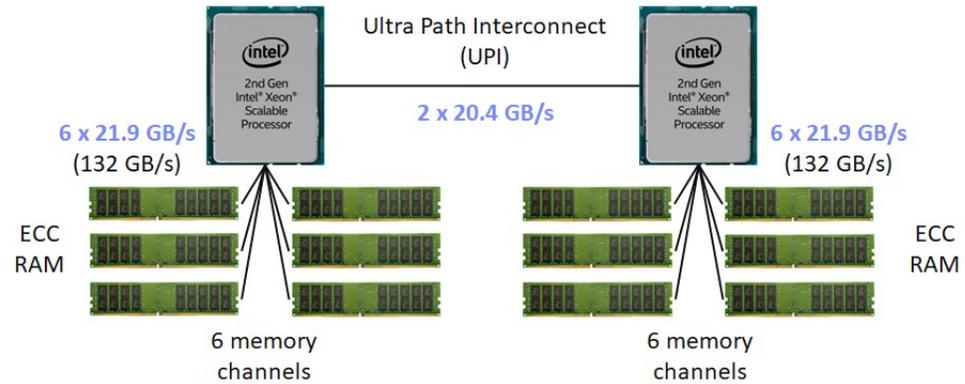
Workload

- Matrix-vector Multiplication (X %*% v)
- X: 1,000,000 x 1,000 in dense FP64 (double)

Costs

- Determine data/compute workload, convert to time

$$C = \max(8GB / 264GB/s, 2GFLOP / 3.85TFLOP/s)$$
$$= \max(30.3ms, 0.5ms) = 30.3ms$$



cpufetch output:

```
Name: Intel(R) Xeon(R) Gold 6238R CPU @ 2.20GHz
Microarchitecture: Cascade Lake
Technology: 14nm
Max Frequency: 4.000 GHz
Sockets: 2
Cores: 28 cores (56 threads)
Cores (Total): 56 cores (112 threads)
AVX: AVX,AVX2,AVX512
FMA: FMA3
L1i Size: 32KB (1.75MB Total)
L1d Size: 32KB (1.75MB Total)
L2 Size: 1MB (56MB Total)
L3 Size: 38.5MB (77MB Total)
Peak Performance: 14.34 TFLOP/s
```

FP32 at
max freq

Excursus: Differentiable Programming



Overview Differentiable Programming

- Adoption of auto differentiation concept from ML systems to PLs
- Yann LeCun (Jan 2018)

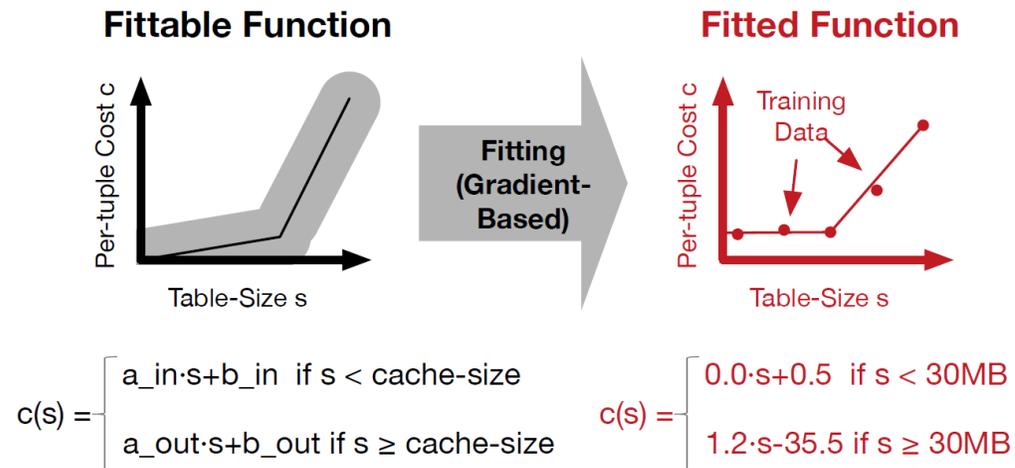
“It's really very much like a regular prog[ra]m, except it's parameterized, automatically differentiated, and trainable/optimizable.”

Example DBMS Fitting

- Implement DBMS components as **differentiable functions**
- E.g.: cost model components
- Q: **What about guarantees** (memory, size)?



[Benjamin Hilprecht et al: DBMS Fitting: Why should we learn what we already know? **CIDR 2020**]



2min BREAK and TEST YOURSELF



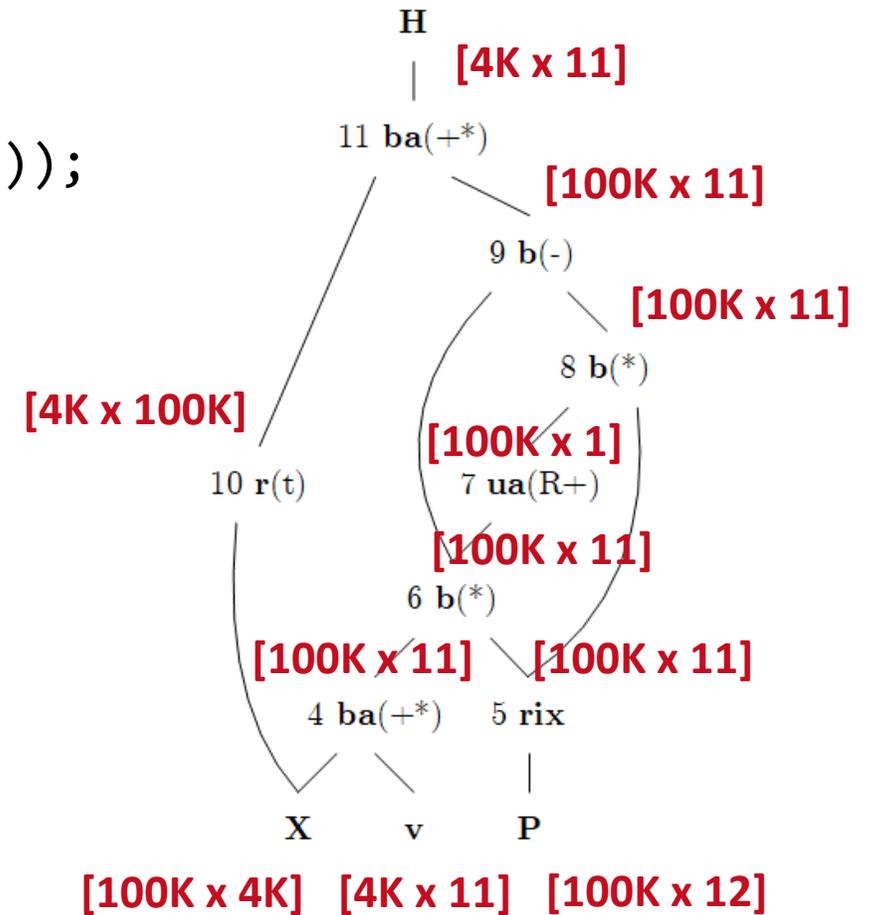
Expression $Q = P[, 1:K] * (X \%*\% v);$
MLogReg $H = t(X) \%*\% (Q - P[, 1:K] * (rowSums(Q) \%*\% matrix(1,1,K)));$

Compiled DAG

- X: 100,000 x 4,000 / nnz = 1,365,000
- v: 4,000 x 11
- P: 100,000 x 12 (K=11, 12 classes)

Q & A

- **What are the dimensions and sparsity of all intermediates?**
- **What rewrites have been applied Expression → DAG?**
→ CSE P[,1:K], rm vector replication
- **What other rewrites are possible if ncol(v)==1?**
→ rm rowsums(), factorize ((1-P[,1:K])*Q) & ((1-P[,1:K])*P[,1:K])



Rewrites (and Operator Selection)

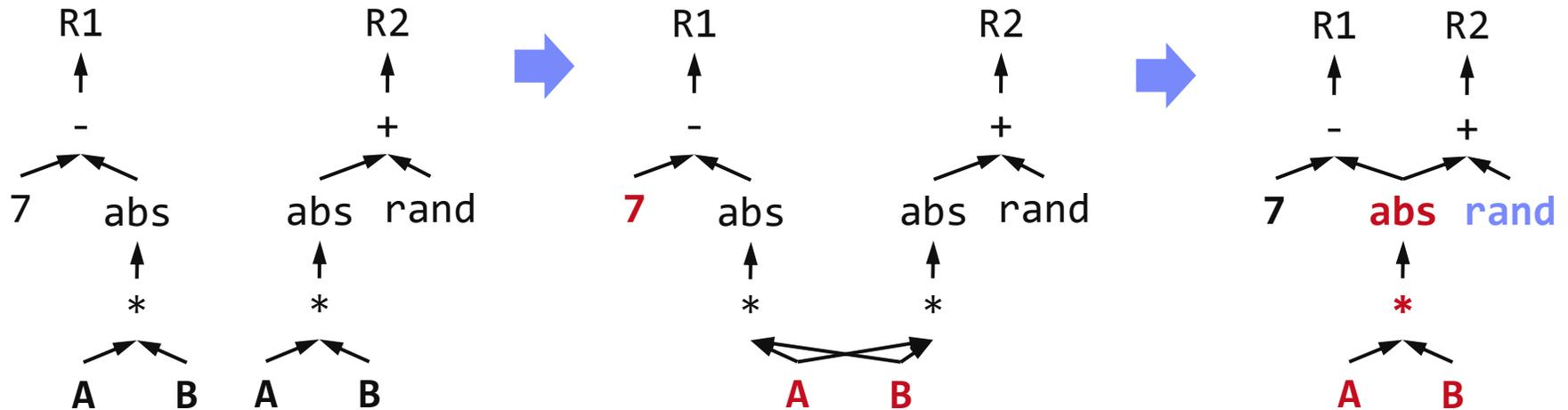
▪ #1 Common Subexpression Elimination (CSE)

- **Step 1:** Collect and **replace leaf nodes** (variable reads and literals)
- **Step 2:** recursively **remove CSEs bottom-up** starting at the leafs by merging nodes with same inputs (**beware non-determinism**)

$$R1 = 7 - \text{abs}(A * B)$$

$$R2 = \text{abs}(A * B) + \text{rand}()$$

▪ Example:



Traditional PL Rewrites, cont.

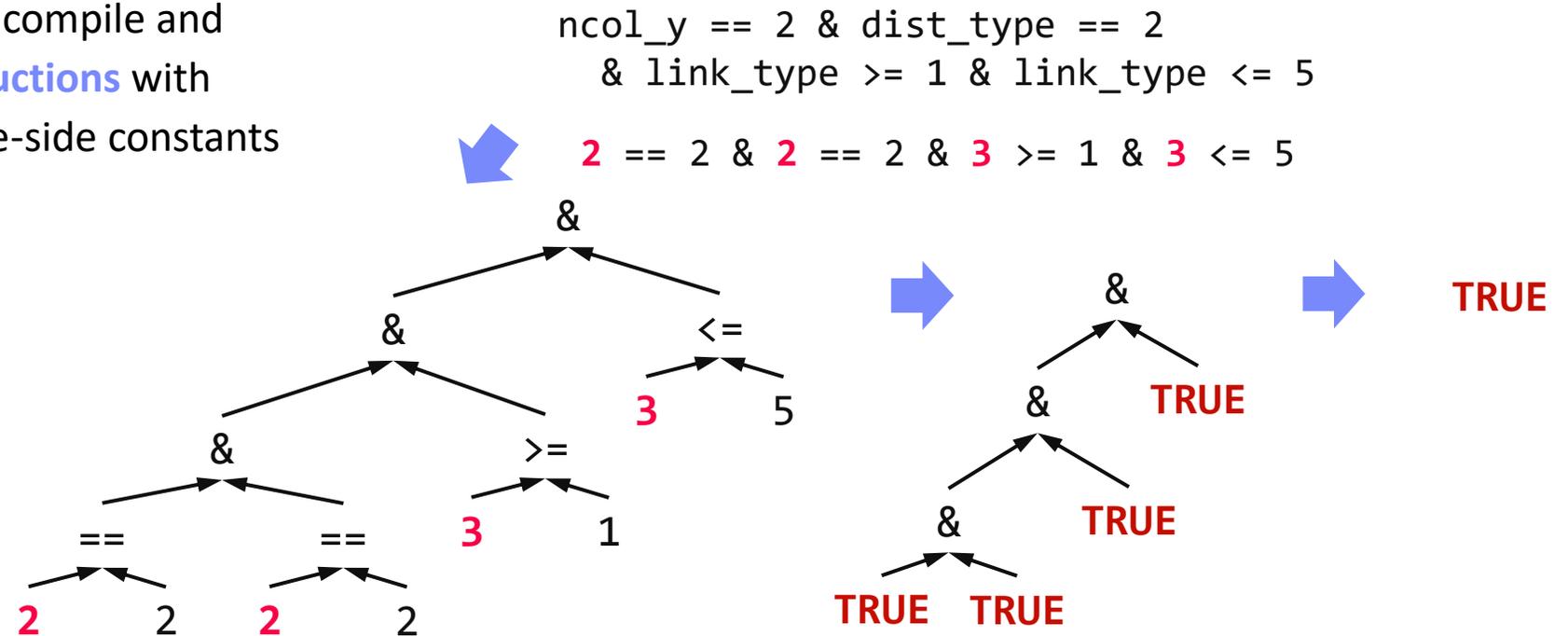
[A. V. Aho, M. S. Lam, R. Sethi, and J. D. Ullman. Compilers – Principles, Techniques, & Tools. Addison-Wesley, 2007]



Turing Award '20

#2 Constant Folding

- After constant propagation, fold sub-DAGs over literals into a single literal
- Approach: **recursively** compile and **execute runtime instructions** with special handling of one-side constants
- Example (GLM Binomial probit):



▪ #3 Branch Removal

- Applied after **constant propagation** and **constant folding**
- **True predicate**: replace if statement block with if-body blocks
- **False predicate**: replace if statement block with else-body block, or remove

▪ #4 Merge of Statement Blocks

- **Merge sequences of unconditional blocks** (s1,s2) into a single block
- Connect matching DAG roots of s1 with DAG inputs of s2

▪ #5 Dead Code Elimination

- Backwards pass through program to eliminate operations that create variables which are not used in subsequent statement blocks

LinregDS (Direct Solve)

```
X = read($1);
y = read($2);
intercept = 0;
lambda = 0.001;
...
FALSE
if( intercept == 1 ) {
    ones = matrix(1, nrow(X), 1);
    X = cbind(X, ones);
}
I = matrix(1, ncol(X), 1);
A = t(X) %*% X + diag(I)*lambda;
b = t(X) %*% y;
beta = solve(A, b);
...
write(beta, $4);
```

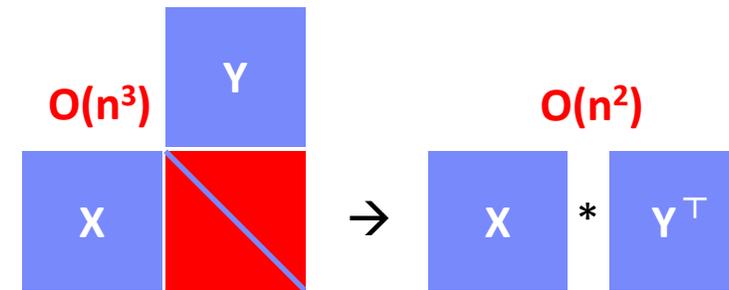
Static/Dynamic Simplification Rewrites

[Matthias Boehm et al: [SystemML's Optimizer: Plan Generation for Large-Scale Machine Learning Programs](#). *IEEE Data Eng. Bull* 2014]



Examples of Static Rewrites

- $\text{trace}(X\%*\%Y) \rightarrow \text{sum}(X*\mathbf{t}(Y))$
- $\text{sum}(X+Y) \rightarrow \text{sum}(X)+\text{sum}(Y)$
- $(X\%*\%Y)[7,3] \rightarrow X[7,]\%*\%Y[,3]$
- $\text{sum}(\mathbf{t}(X)) \rightarrow \text{sum}(X)$
- $\text{rand()}*7 \rightarrow \text{rand}(, \text{min}=0, \text{max}=7)$
- $\text{sum}(\text{lambda}*X) \rightarrow \text{lambda} * \text{sum}(X);$



Examples of Dynamic Rewrites

- $\mathbf{t}(X) \%*\% y \rightarrow \mathbf{t}(\mathbf{t}(y) \%*\% X)$ **s.t. costs**
- $X[a:b,c:d]=Y \rightarrow X = Y$ **iff** $\text{dims}(X)=\text{dims}(Y)$
- $(\dots) * X \rightarrow \text{matrix}(0, \text{nrow}(X), \text{ncol}(X))$ **iff** $\text{nnz}(X)=0$
- $\text{sum}(X^2) \rightarrow \mathbf{t}(X)\%*\%X; \text{rowSums}(X) \rightarrow X$ **iff** $\text{ncol}(X)=1$
- $\text{sum}(X\%*\%Y) \rightarrow \text{sum}(\mathbf{t}(\text{colSums}(X))*\text{rowSums}(Y))$ **iff** $\text{ncol}(X)>\mathbf{t}$

Static/Dynamic Simplification Rewrites, cont.

[Rasmus Munk Larsen, Tatiana Shpeisman:
TensorFlow Graph Optimizations,
Guest Lecture Stanford 2019]



TF Constant Push-Down

- $\text{Add}(c1, \text{Add}(x, c2)) \rightarrow \text{Add}(x, c1+c2)$
- $\text{ConvND}(c1*x, c2) \rightarrow \text{ConvND}(x, c1*c2)$

TF Arithmetic Simplifications

- Flattening: $a+b+c+d \rightarrow \text{AddN}(a, b, c, d)$
- Hoisting: $\text{AddN}(x * a, b * x, x * c) \rightarrow x * \text{AddN}(a+b+c)$
- Reduce Nodes Numeric: $x+x+x \rightarrow 3*x$
- Reduce Nodes Logical: $!(x > y) \rightarrow x \leq y$

TF Broadcast Minimization

- $(M1+s1) + (M2+s2) \rightarrow (M1+M2) + (s1+s2)$

TF Better use of Intrinsic

- $\text{Matmul}(\text{Transpose}(X), Y) \rightarrow \text{Matmul}(X, Y, \text{transpose_x}=\text{True})$

SystemML/SystemDS
RewriteElementwise-
MultChainOptimization
(orders and collapses matrix,
vector, scalar op chains)

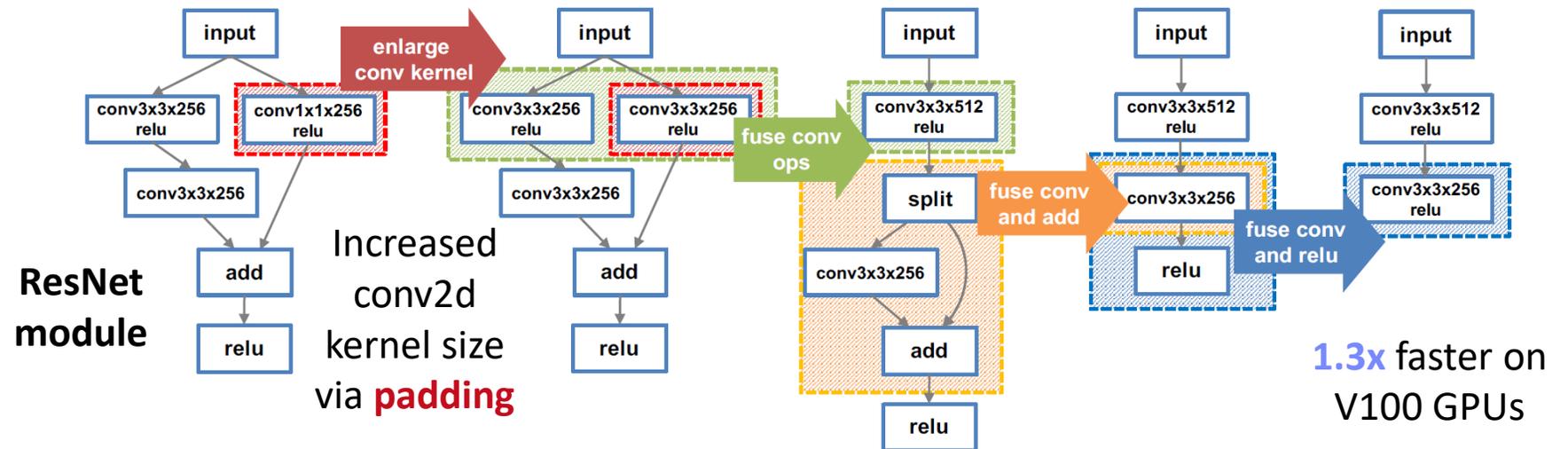
Static/Dynamic Simplification Rewrites, cont.



Relaxed DNN Graph Substitutions

- Allow substitutions that preserve semantics, no matter if **faster/slower**
- Backtracking search

[Zhihao Jia, James J. Thomas, Todd Warszawski, Mingyu Gao, Matei Zaharia, Alex Aiken: Optimizing DNN Computation with Relaxed Graph Substitutions. **MLSys 2019**]



Additional Algorithms

- Partial order of substitutions w/ pruning
- Dynamic programming → substitutions

[Jingzhi Fang, Yanyan Shen, Yue Wang, Lei Chen: Optimizing DNN Computation Graph using Graph Substitutions. **PVLDB 13(11) 2020**]



Static/Dynamic Simplification Rewrites, cont.



PYTORCH

■ Rewrites in PyTorch (Torch Script JIT)

- **Misc:** Canonicalization, erase number types and no-ops
- Fuse linear, fuse relu, fuse graph pipeline
- Inlining and loop unrolling
- **Concatenation and fusion rewrites**
- **Peephole simplifications** (e.g., dtype mgmt)

[https://github.com/pytorch/pytorch/blob/master/torch/csrc/jit/passes/subgraph_rewrite.cpp]

peephole.cpp	[Reland] Move torch::make_unique to ...	8 months ago
peephole.h	[Refactoring] make transformations re...	3 years ago
peephole_alias_sensitive.cpp	[Reland] Move torch::make_unique to ...	8 months ago
peephole_alias_sensitive.h	[JIT] make x (+ or -) 0 and x (* or /) 1 p...	3 years ago
peephole_dict_idioms.cpp	Apply Clang-Tidy readability-containe...	last year
peephole_dict_idioms.h	[Static Runtime] Add pass to eliminate...	3 years ago
peephole_list_idioms.cpp	[Reland] Move torch::make_unique to ...	8 months ago
peephole_list_idioms.h	[JIT] Re-land "Add aten::slice optimizat...	3 years ago
peephole_non_tensor.cpp	[Reland2] fix missing-prototypes warni...	last year
peephole_non_tensor.h	Factor out non tensor peephole (#559...	3 years ago

```
36 void SubgraphRewriter::RegisterDefaultPatterns() {
37     // TODO: Add actual patterns (like Conv-Relu).
38     RegisterRewritePattern(
39         R"IR(
40 graph(%x, %w, %b):
41     %c = aten::conv(%x, %w, %b)
42     %r = aten::relu(%c)
43     return (%r))IR",
44         R"IR(
45 graph(%x, %w, %b):
46     %r = aten::convrelu(%x, %w, %b)
47     return (%r))IR",
48         {"r", "c"});
49 }
```

subgraph_rewrite.cpp
(extracted Mar 17, 2022)

[<https://github.com/pytorch/pytorch/tree/main/torch/csrc/jit/passes>,
extracted May 01, 2024]



Vectorization and Incremental Computation

- **Loop Transformations**
(e.g., **OptiML**, **SystemML**)

```
for(i in a:b)
  X[i,1] = Y[i,2] + Z[i,1]
```

- **Loop vectorization**

- Loop hoisting

→ $X[a:b,1] = Y[a:b,2] + Z[a:b,1]$

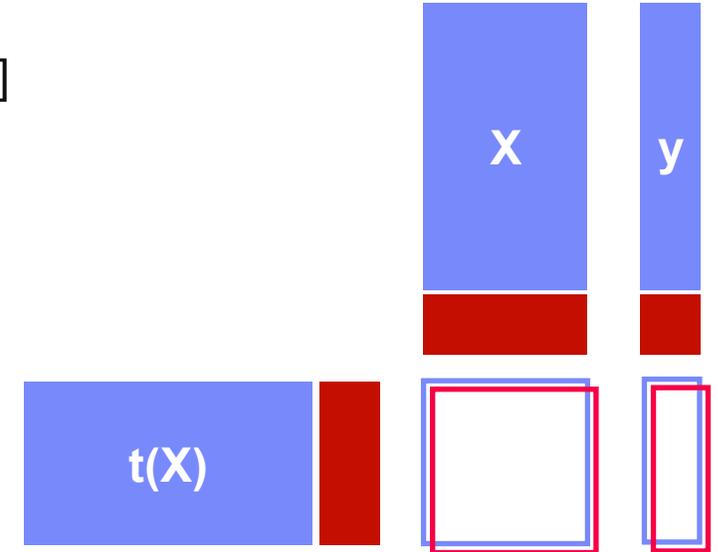
- **Incremental Computations**

- **Delta update rules** (e.g., **LINVIEW**, **factorized**)

- Incremental iterations (e.g., **Flink**)

$$A = t(X) \%* \% X + t(\Delta X) \%* \% \Delta X$$

$$b = t(X) \%* \% y + t(\Delta X) \%* \% \Delta y$$



- **“Decremental”/Unlearning (GDPR)**



[Sebastian Schelter: "Amnesia" – Machine Learning Models That Can Forget User Data Very Fast. **CIDR 2020**]



[Sebastian Schelter, Stefan Grafberger, Ted Dunning: HedgeCut: Maintaining Randomised Trees for Low-Latency Machine Unlearning. **SIGMOD 2021**]

Example: Cumulative Aggregate via Strawman Scripts

- But: R, Julia, Matlab, SystemDS, NumPy all provide `cumsum(X)`, etc

```
1: cumsumN2 = function(Matrix[Double] A)
2:   return(Matrix[Double] B)
3: {
4:   B = A; csums = matrix(0,1,ncol(A));
5:   for( i in 1:nrow(A) ) {
6:     csums = csums + A[i,];
7:     B[i,] = csums;
8:   }
9: } copy-on-write → O(n2)
```

```
1: cumsumNlogN = function(Matrix[Double] A)
2:   return(Matrix[Double] B)
3: {
4:   B = A; m = nrow(A); k = 1;
5:   while( k < m ) {
6:     B[(k+1):m,] = B[(k+1):m,] + B[1:(m-k),];
7:     k = 2 * k;
8:   }
9: } → O(n log n)
```

Update in place (w/ $O(n)$)

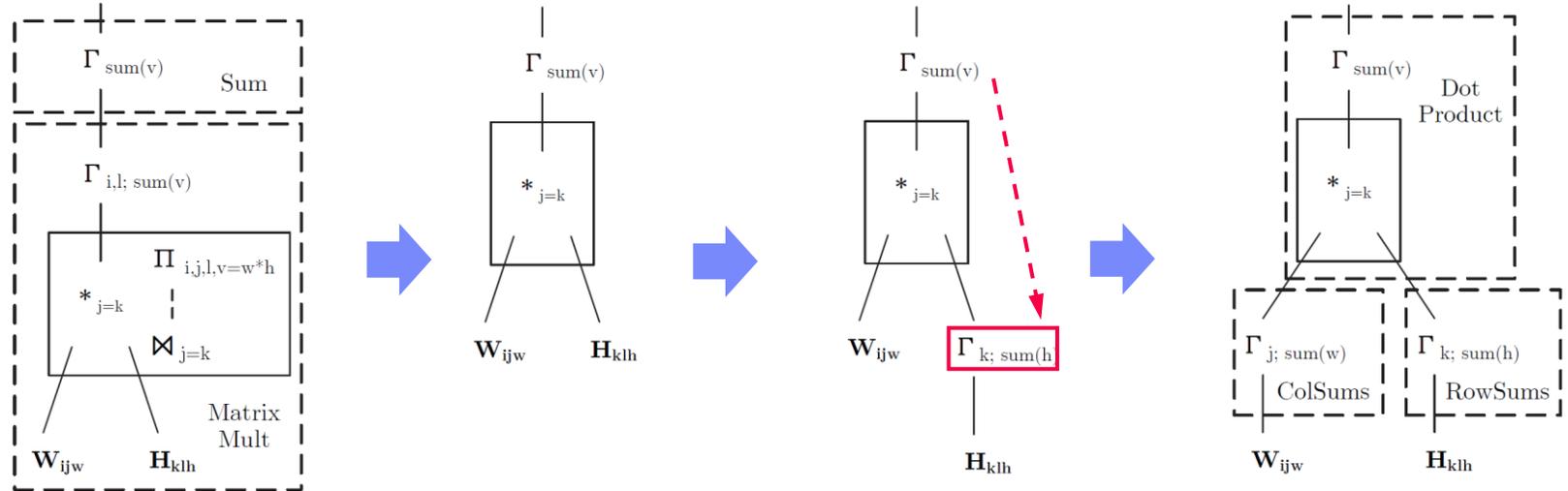
- SystemDS: via rewrites (**why do the above scripts apply?**)
- R: via reference counting
- Julia: by default, otherwise explicit **B = copy(A)** necessary



Excursus: Automatic Rewrite Generation

- **SPOOF/SPORES (Sum-Product Optim.)**

- **Break up** LA ops into basic ops (RA)
- **Elementary sum-product/RA rewrites**
- **Example:**
 $\text{sum}(W\%*\%H)$

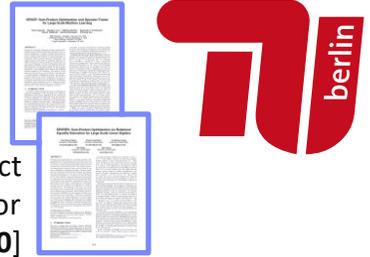


- **TASO (Super Optimization)**

- List of operator specifications and properties
- Automatic **generation/verification of graph substitutions** and **data layouts** via cost-based backtracking search

[Tarek Elgamal et al: SPOOF: Sum-Product Optimization and Operator Fusion for Large-Scale Machine Learning. **CIDR 2017**]

[Yisu Remy Wang et al: SPORES: Sum-Product Optimization via Relational Equality Saturation for Large Scale Linear Algebra. **PVLDB 13(11) 2020**]



[Zhihao Jia et al: TASO: optimizing deep learning computation with automatic generation of graph substitutions. **SOSP 2019**]

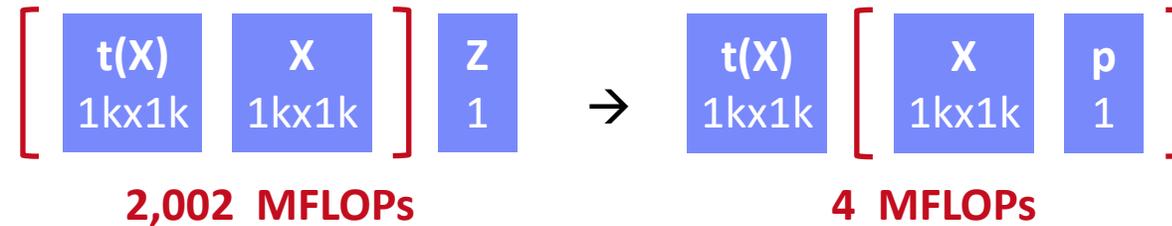


Matrix Multiplication Chain Optimization



Optimization Problem

- Matrix multiplication chain of n matrices M_1, M_2, \dots, M_n (associative)
- Optimal parenthesization of the product $M_1 M_2 \dots M_n$



Size propagation and sparsity estimation

Search Space Characteristics

- Naïve exhaustive: Catalan numbers $\rightarrow \Omega(4^n / n^{3/2})$
- DP applies: (1) optimal substructure, (2) overlapping subproblems
- Textbook DP algorithm: $\Theta(n^3)$ time, $\Theta(n^2)$ space
 - Examples: **SystemML** '14, **RIOT** ('09 I/O costs), **SpMachO** ('15 sparsity)
- Best known: $O(n \log n)$

n	C_{n-1}
5	14
10	4,862
15	2,674,440
20	1,767,263,190
25	1,289,904,147,324

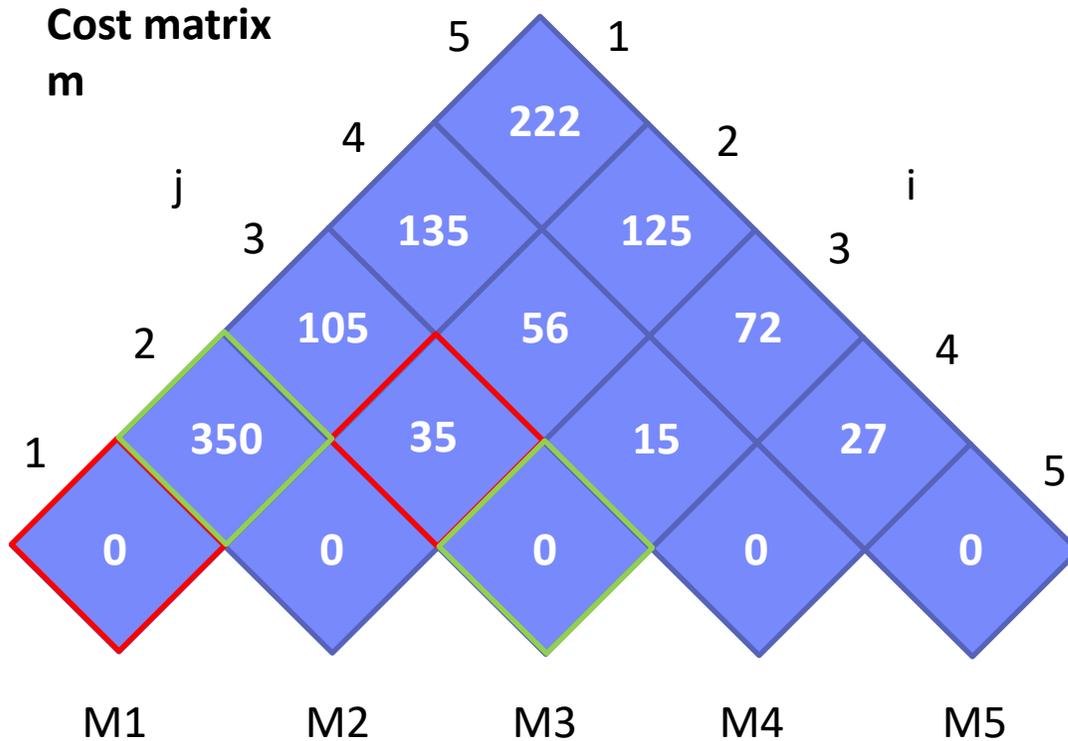


[T. C. Hu, M. T. Shing: Computation of Matrix Chain Products. Part II. **SIAM J. Comput.** 13(2), 1984]

Matrix Multiplication Chain Optimization, cont.



M1	M2	M3	M4	M5
10x7	7x5	5x1	1x3	3x9



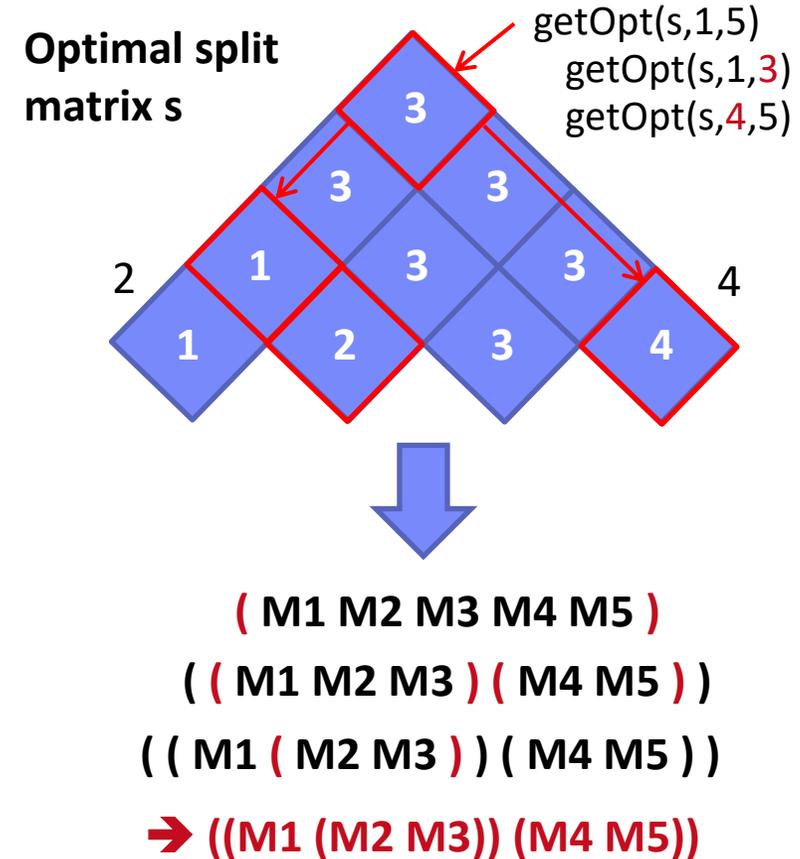
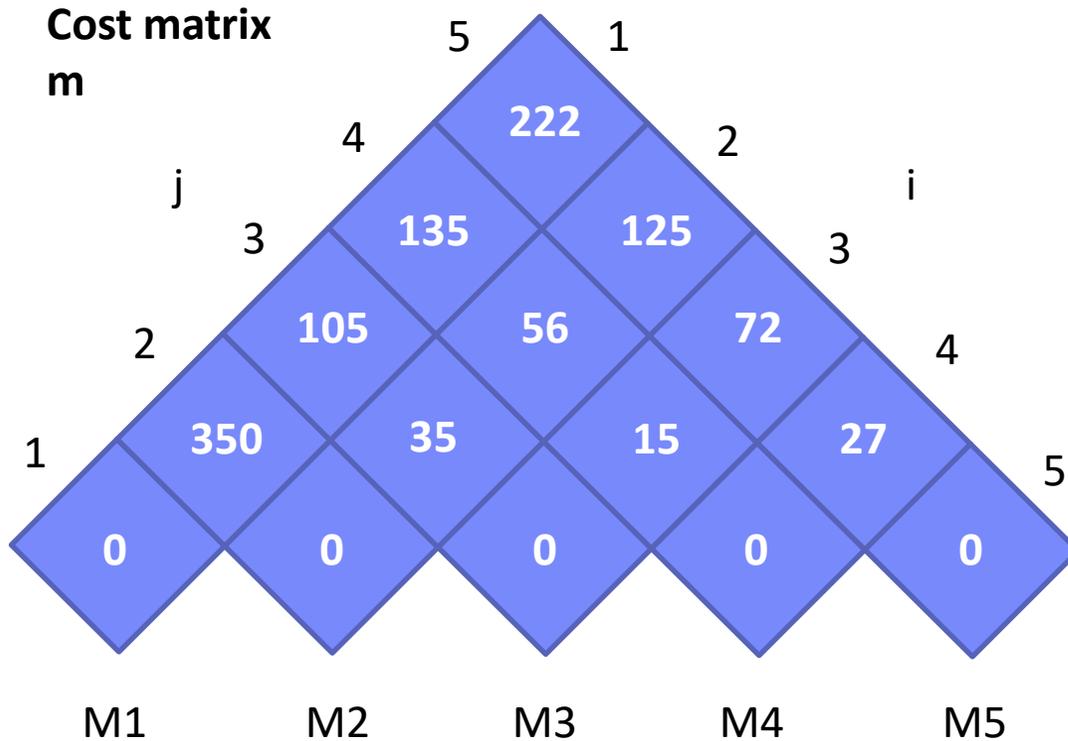
$$\begin{aligned}
 m[1,3] &= \min(\\
 &\quad m[1,1] + m[2,3] + p_1 p_2 p_4, \\
 &\quad m[1,2] + m[3,3] + p_1 p_3 p_4) \\
 &= \min(\\
 &\quad 0 + 35 + 10 * 7 * 1, \quad 105, \\
 &\quad 350 + 0 + 10 * 5 * 1) \quad 400)
 \end{aligned}$$

[T. H. Cormen, C. E. Leiserson, R. L. Rivest, C. Stein: Introduction to Algorithms, Third Edition, The MIT Press, pages 370-377, 2009]

Matrix Multiplication Chain Optimization, cont.



M1	M2	M3	M4	M5
10x7	7x5	5x1	1x3	3x9



→ Open questions: DAGs; other operations, sparsity, joint opt w/ rewrites, CSE, fusion, and physical operators

Sparsity-aware MMChain Optimization



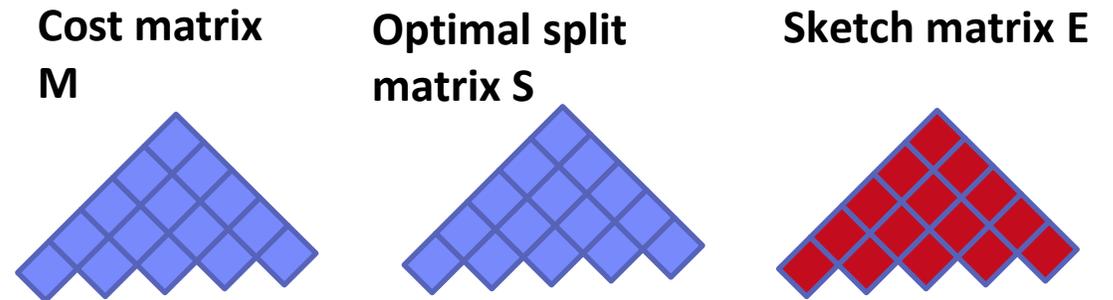
Sparsity-aware MMChain Opt

- Additional $n \times n$ sketch matrix e
- Sketch propagation for optimal subchains (currently for all chains)
- Modified cost computation via MNC sketches (**number FLOPs for sparse** instead of dense mm)

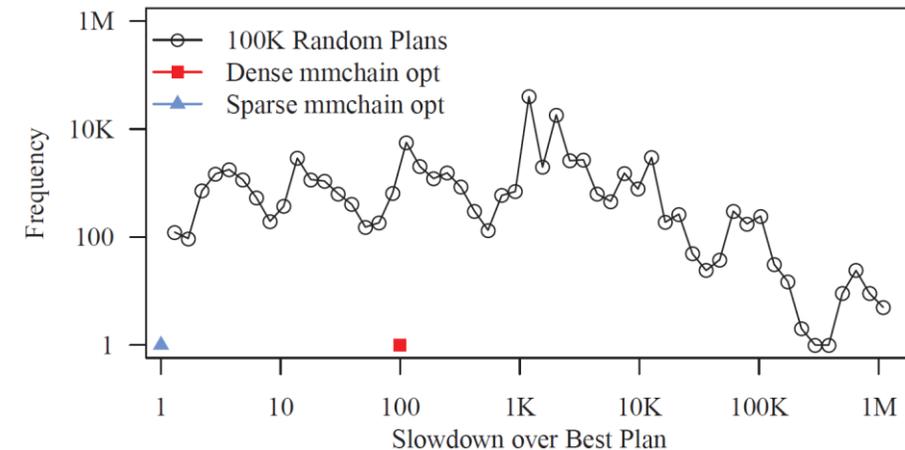
$$C_{i,j} = \min_{k \in [i,j-1]} (C_{i,k} + C_{k+1,j} + E_{i,k} \cdot h^c E_{k+1,j} \cdot h^r)$$



[Johanna Sommer, Matthias Boehm, Alexandre V. Evfimievski, Berthold Reinwald, Peter J. Haas: **MNC**: Structure-Exploiting Sparsity Estimation for Matrix Expressions. **SIGMOD 2019**]



Example: $n=20$ matrices

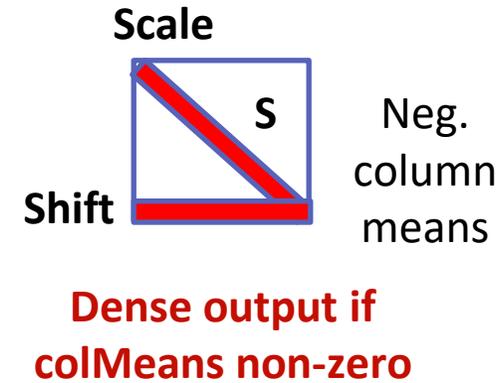
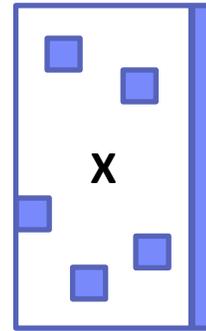


Sparsity-aware MMChain Optimization, cont.



Example: Deferred Standardization

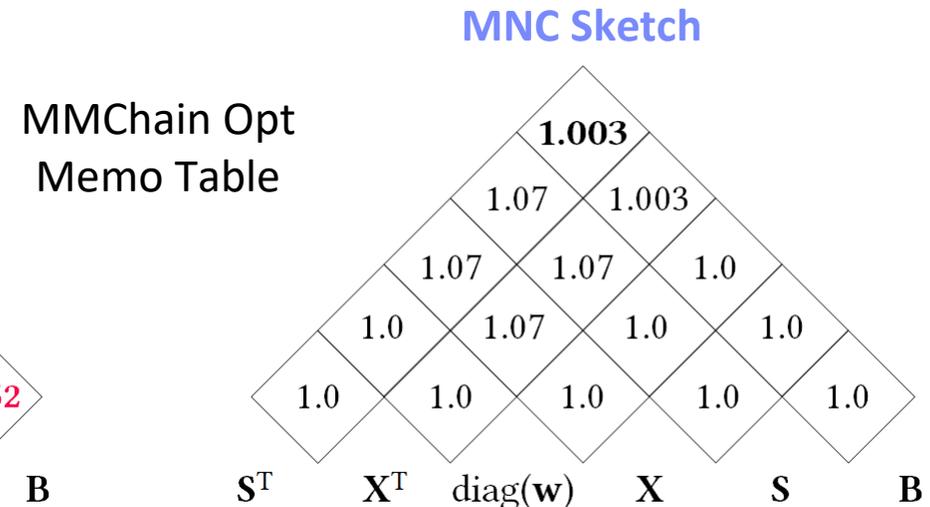
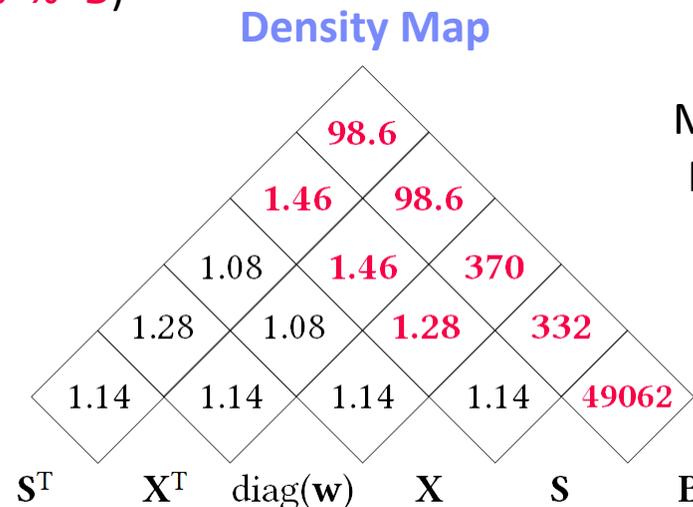
- Mean subtraction is densifying
- Substitute standardized X with $X \%*\% S$ and optimize mm chain



Accuracy of Sparsity Estimation

- Example Expression
(substitute X with $X \%*\% S$)
- Mnist1m
- Error Density Map vs MNC Sketch

$$t(X) \%*\% \text{diag}(w) \%*\% X \%*\% B \rightarrow t(S) \%*\% t(X) \%*\% \text{diag}(w) \%*\% X \%*\% S \%*\% B$$

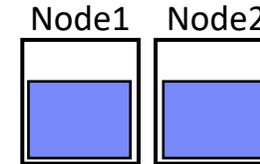


Physical Rewrites and Optimizations



■ Distributed Caching

- Redundant compute vs. memory consumption and I/O
- #1 Cache intermediates w/ multiple refs (Emma)
- #2 Cache initial read and read-only loop vars (SystemML)



■ Partitioning

- Many frameworks exploit co-partitioning for efficient joins
- #1 Partitioning-exploiting operators (SystemML, Emma, Samsara)
- #2 Inject partitioning to avoid shuffle per iteration (SystemML)
- #3 Plan-specific data partitioning (SystemML, Dmac, Kasen)

Example Hash Partitioning:
For all (k,v) of R:
 $\text{hash}(k) \% \text{numPartitions} \rightarrow \text{pid}$

■ Other Data Flow Optimizations (Emma)

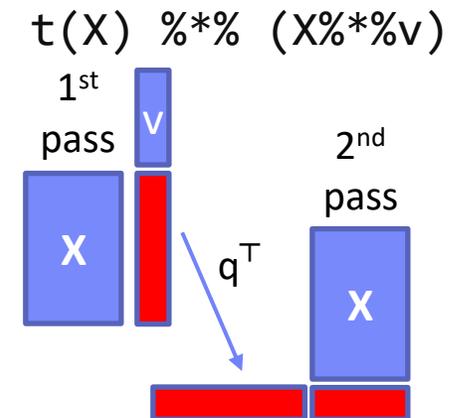
- #1 Exists unnesting (e.g., filter w/ broadcast \rightarrow join)
- #2 Fold-group fusion (e.g., groupByKey \rightarrow reduceByKey)

■ Physical Operator Selection

Physical Operator Selection



- **Common Selection Criteria**
 - **Data and cluster characteristics** (e.g., data size/shape, memory, parallelism)
 - **Matrix/operation properties** (e.g., diagonal/symmetric, sparse-safe ops)
 - **Data flow properties** (e.g., co-partitioning, co-location, data locality)
- **#0 Local Operators**
 - SystemML `mm`, `tsmm`, `mmchain`; Samsara/Mllib local
- **#1 Special Operators** (special patterns/sparsity)
 - SystemML `tsmm`, `mapmmchain`; Samsara AtA
- **#2 Broadcast-Based Operators** (aka broadcast join)
 - SystemML `mapmm`, `mapmmchain`
- **#3 Co-Partitioning-Based Operators** (aka improved repartition join)
 - SystemML `zipmm`; Emma, Samsara OpAtB
- **#4 Shuffle-Based Operators** (aka repartition join)
 - SystemML `cpmm`, `rmm`; Samsara OpAB



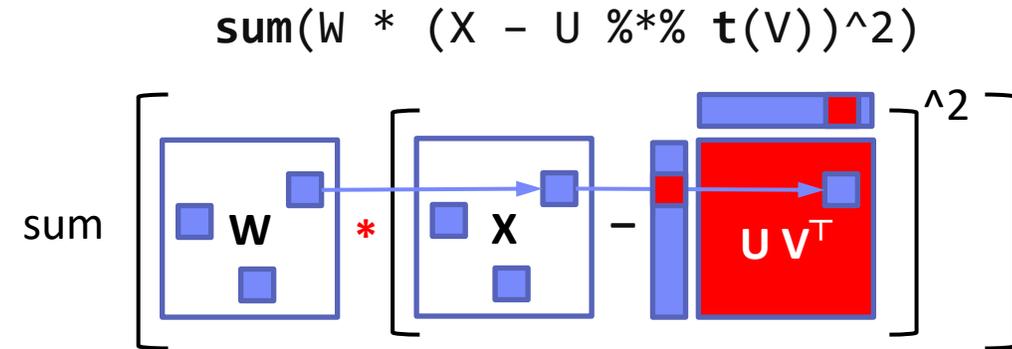
Sparsity-Exploiting Operators



- **Goal:** Avoid dense intermediates and unnecessary computation

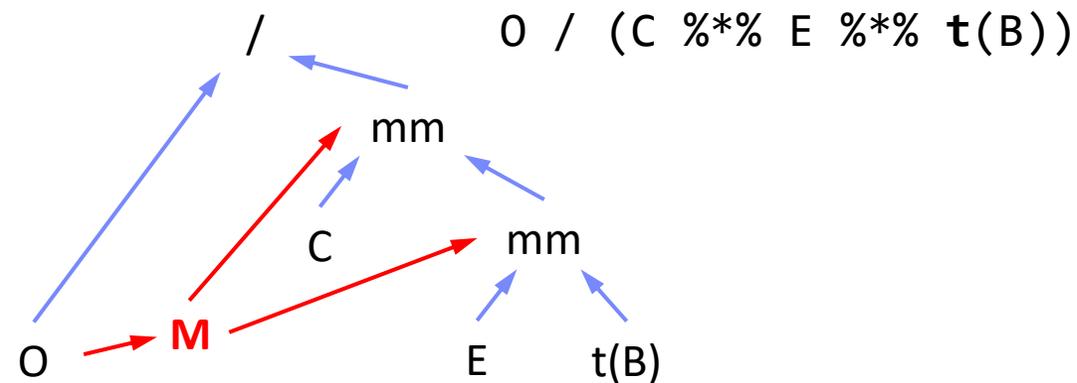
- **#1 Fused Physical Operators**

- E.g., SystemML [PVLDB'16]
wsloss, wceimm, wdivmm
- Selective computation over non-zeros of “sparse driver”



- **#2 Masked Physical Operators**

- E.g., Cumulon MaskMult [SIGMOD'13]
- Create mask of “sparse driver”
- Pass mask to single masked matrix multiply operator



- **Basic compilation overview**
 - **Size inference and cost estimation**
 - **Rewrites and operator selection**
- ➔ **Impact of Size Inference and Costs**
- Advanced optimization of LA programs requires size inference for cost estimation and validity constraints
- ➔ **Ubiquitous Rewrite Opportunities**
- Linear algebra programs have plenty of room for optimization
 - Potential for changed asymptotic behavior
- **Next Lectures**
 - **04 Compilation – Operator Fusion and Runtime Adaptation** [May 16]
(advanced compilation, operator scheduling, JIT compilation, operator fusion / codegen, MLIR)